

Introduction to Numerical Analysis 18.330

Lecture 1:
Introduction
Quadrature

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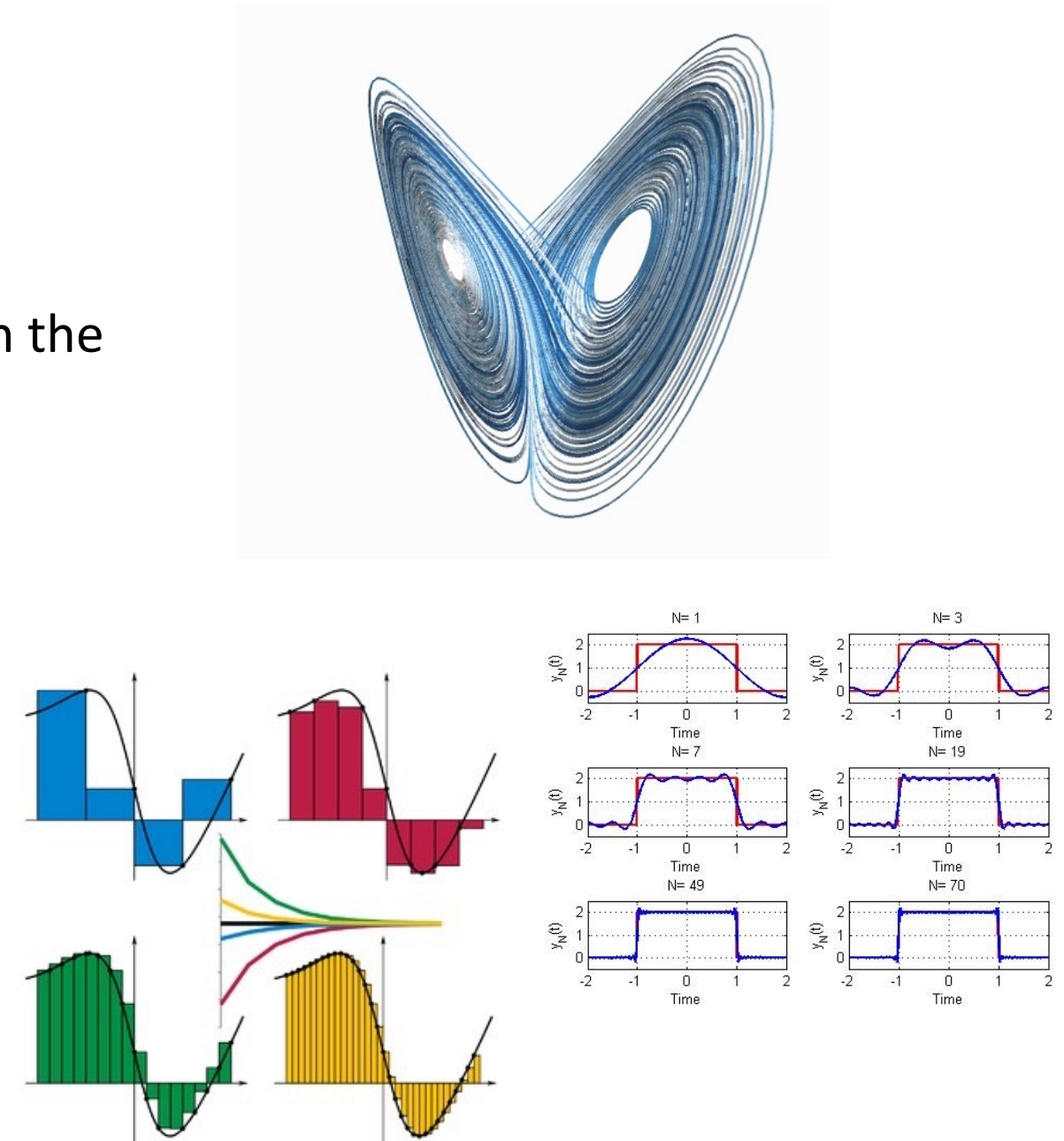
What is Numerical Analysis?

The study of algorithms that implement **continuous** functions as **discrete** objects in the computer, in order to:

- Perform **operations** -- think calculus
- Solve **equations** (algebraic, differential)
- Solve **optimization** problems, including machine learning
- **Infer** models from observations

Math questions about those algorithms:

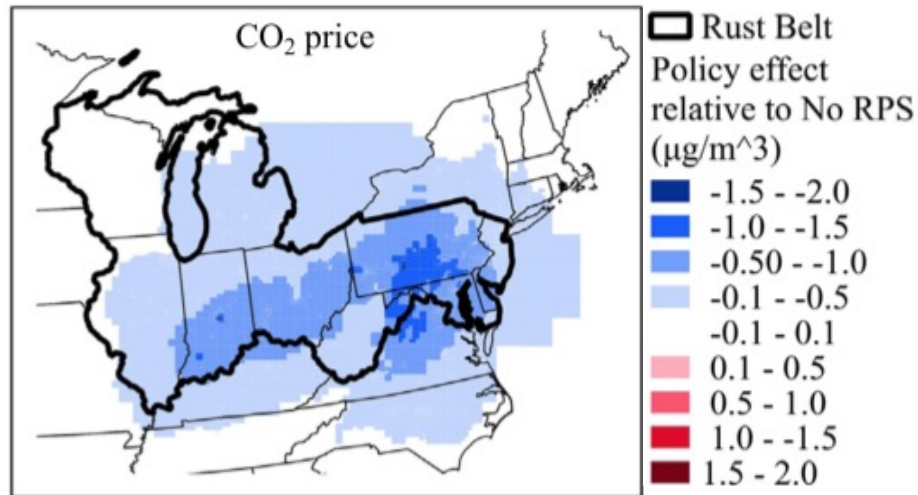
- Effectiveness – **do they work well?**
- Efficiency – **are they fast?**



The real-life context for numerical analysis is **Computational Science and Engineering** (CSE).

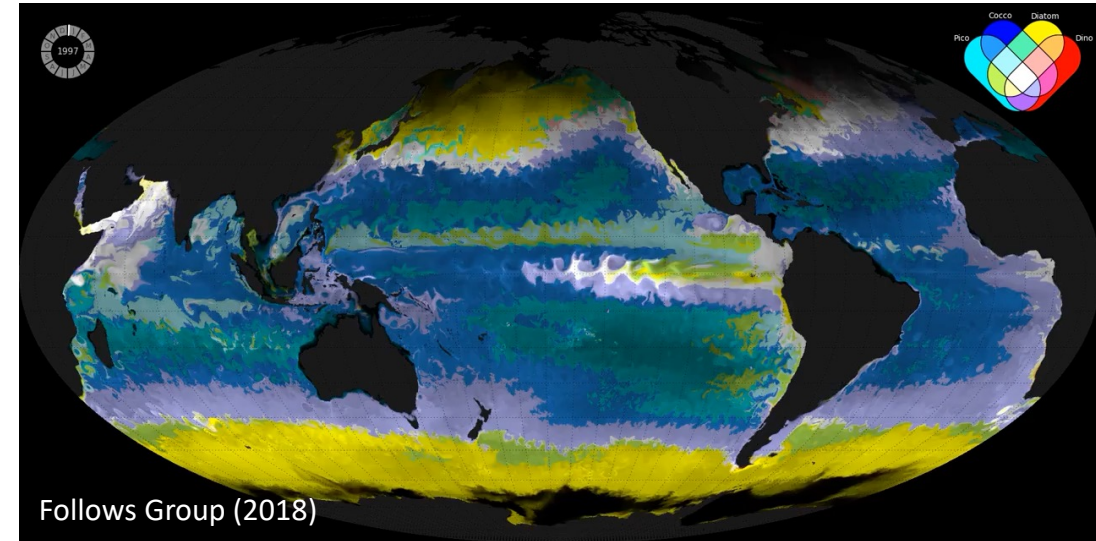
The objective of CSE is to develop and apply computational methods for:

Decision-making for societal challenges



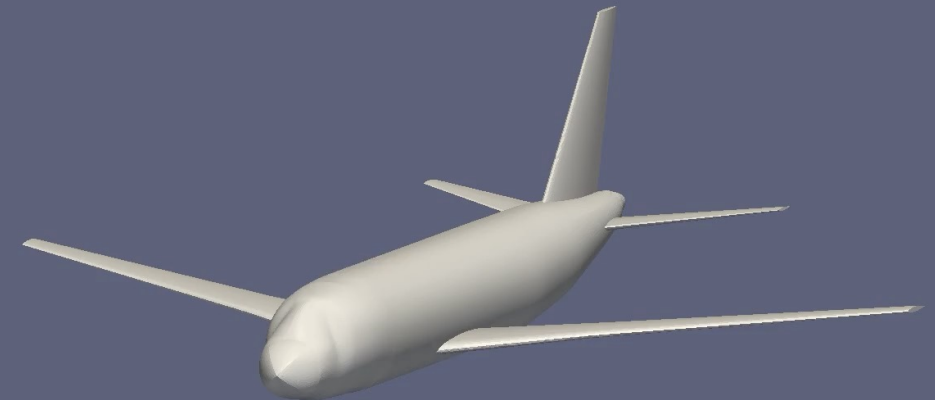
Selin Group (2019)

Scientific discovery



Innovation in engineering & technology

Improving airplane safety through simulation of rupture from life cycle wear

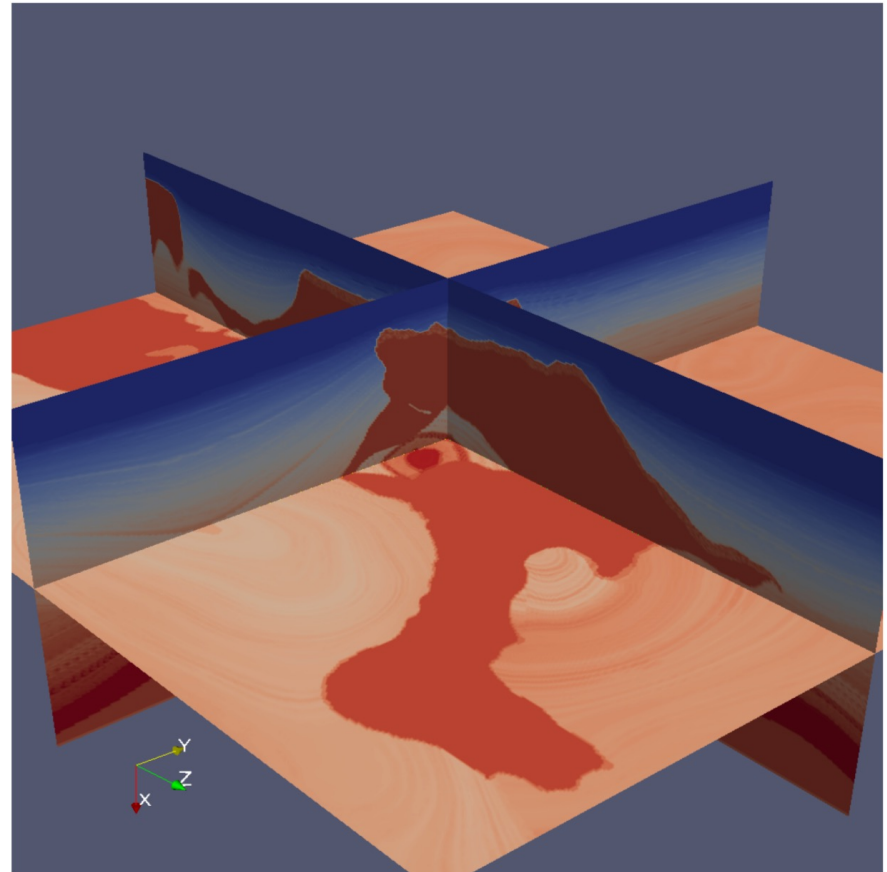
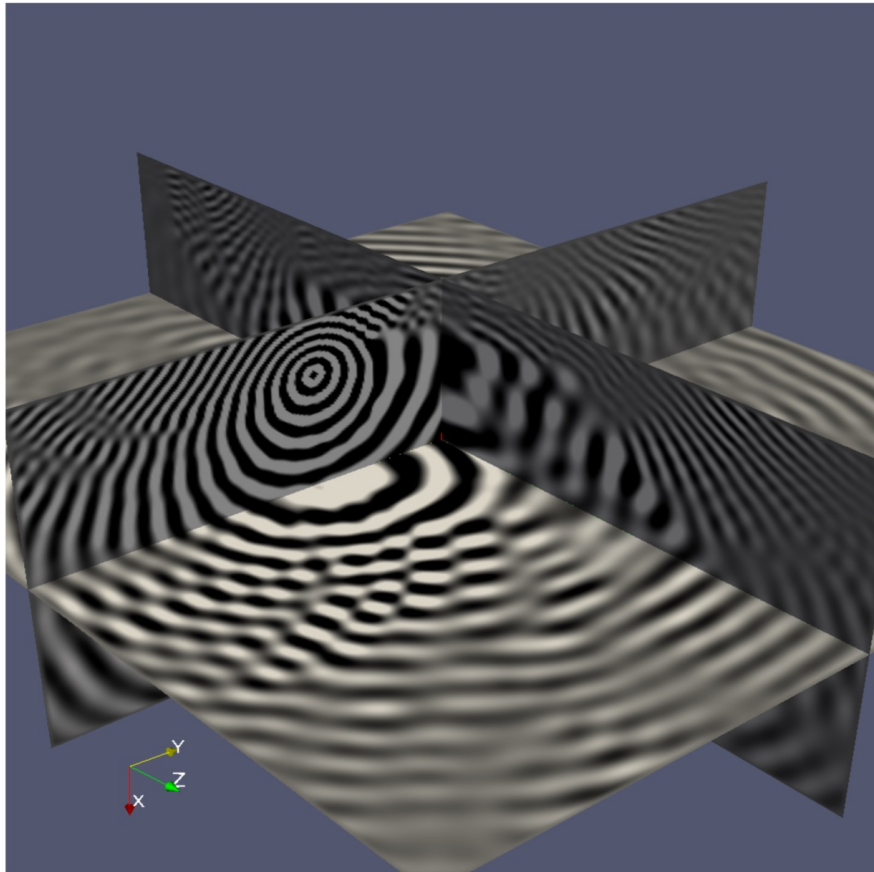


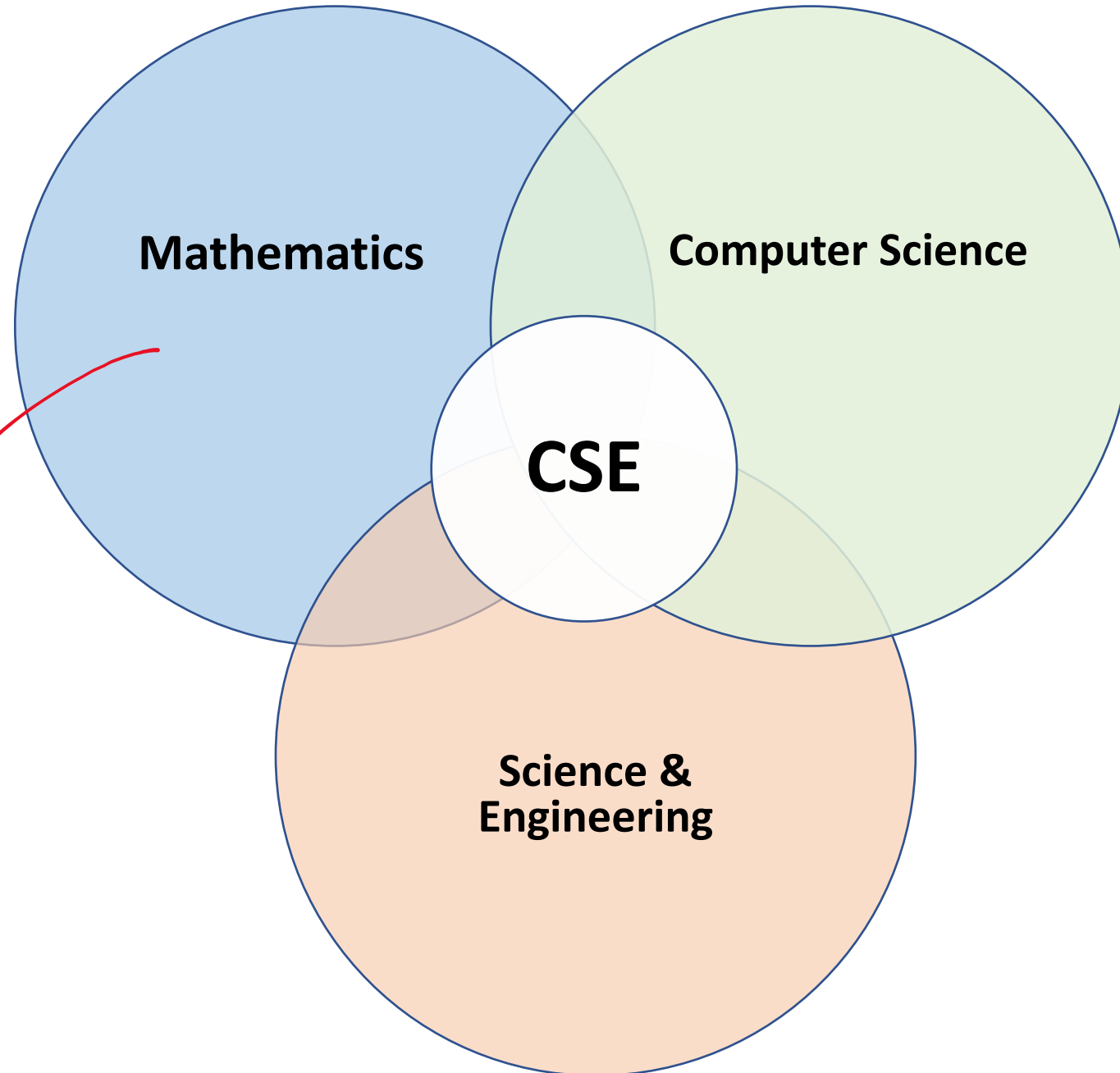
Talamini & Radovitzky (2017)

For instance, my group works on seismic imaging:

How do **elastic waves propagate inside the Earth?**

Can that help build a **3D map of the subsurface?**





Numerical analysis is
(much of) the math
part of CSE

This class

Prerequisites: Calculus at the level of 18.01, 18.02, and 18.03.

Helps but not prereq: Linear algebra at the level of 18.06, programming at the level of 6.0002 or 16.0002 / 18.0002.

Live participation

Everything else on canvas, except Q&A on piazza

Zap me for canvas



Evaluation: 50% homework, 20% in-class midterm, 30% in-class final.

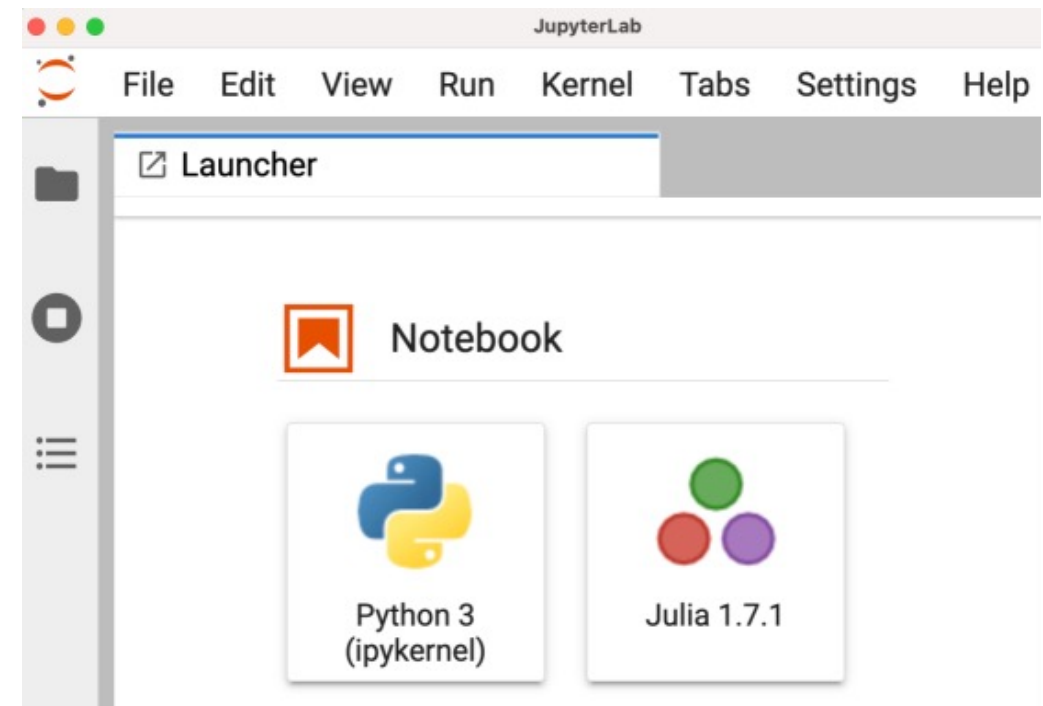
Homework:

No late copy will be allowed. The lowest problem set score will be dropped.

Collaboration is allowed, but the codes and copies you turn in must be original and written by you. We encourage psetpartners.mit.edu for forming study groups.

Programming language: your choice!

- Julia with IJulia notebook (in JupyterLab)
- Python with Spyder or JupyterLab
- Matlab



Resources

Contact us: ldemanet@mit.edu or piazza
(anonymous or not, PM or public)

Office hours on Tuesdays 5-6pm, 2-247

Zoom OH possible, request ahead of time.

Main reference: PDF notes. Code uploaded
through the term.

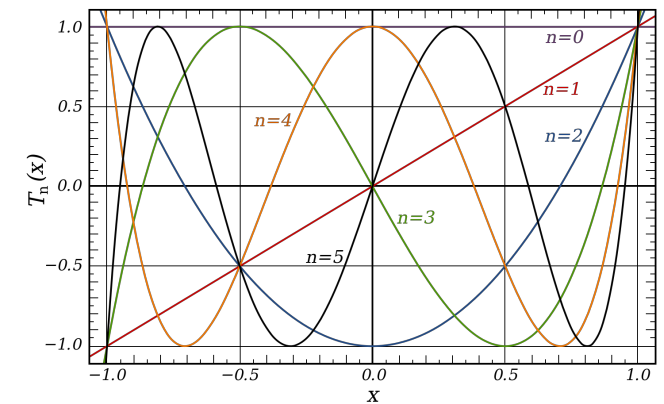
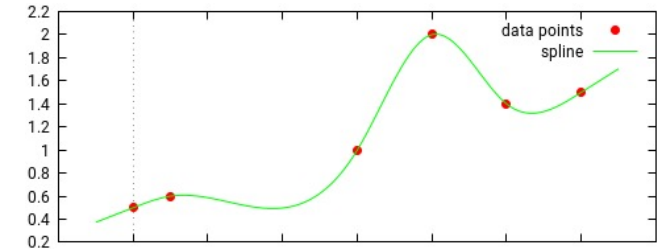
Will add links to (completely optional) books
and other notes.

Zap me for canvas



Topics:

- Sum rules for integrals, difference rules for derivatives
- Interpolation, splines, and a second look at sum/difference rules
- Root finding [tentative]
- Numerical methods for initial-value problems (ODE)
- Numerical methods for boundary-value problems (still ODE)
- Fourier transform, Fourier series, Shannon sampling theory
- Bandlimited interpolation, spectral methods
- Least-squares approximation [tentative]

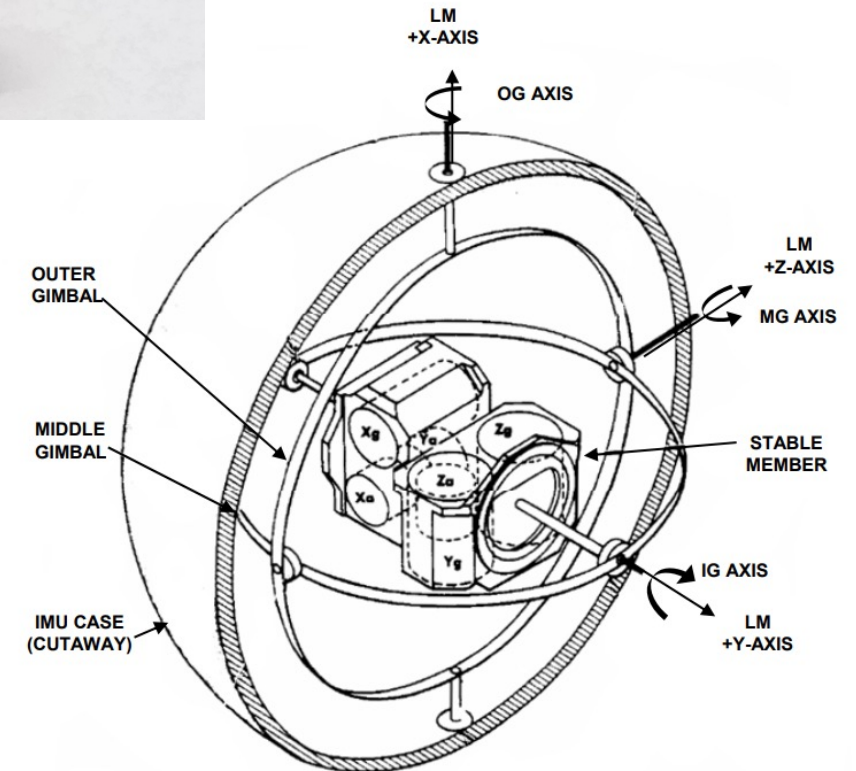
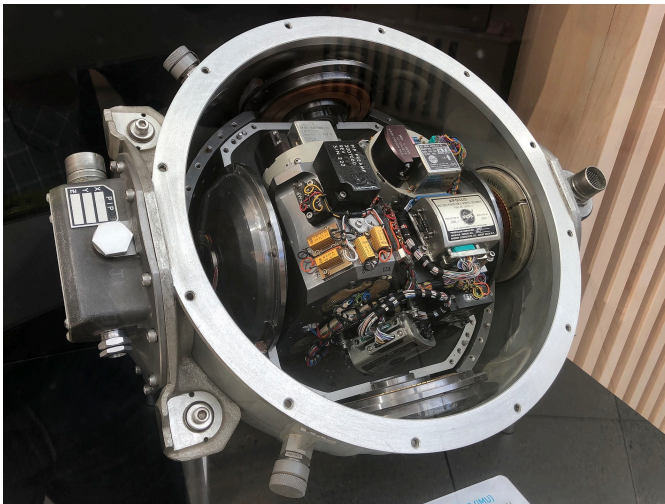


Today: Sum rules for integrals (quadrature)

Example 1: how much snow accumulated in the Boston area?



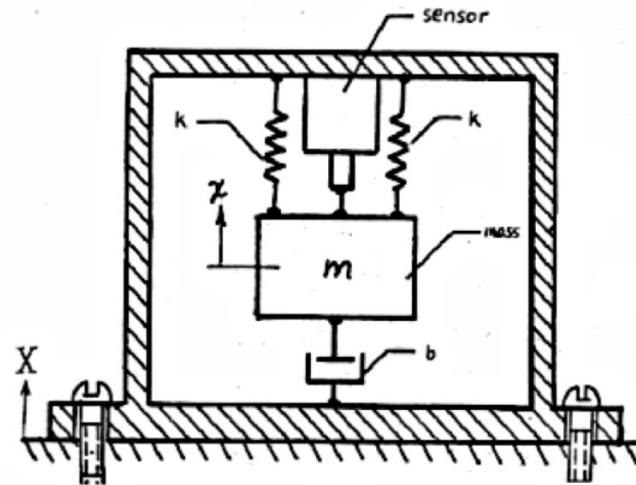
Example 2: find the position of an aircraft or spacecraft



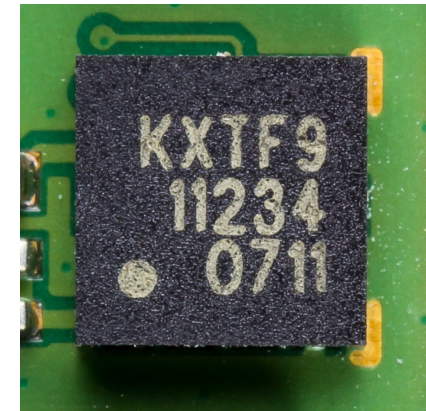
Example 2: how to find the position of an aircraft or spacecraft (without GPS)?

Inertial navigation system (INS): integrate acceleration data twice to get position

Accelerometers measure the deformations of 3 damped springs



Credit: Pocketlab



Credit: Kionix

Correct for orientation and gravity using gyroscopes/compass.

Also used in phones (tilt) and video game controllers

Three kinds of errors:

- **Drift error**: Accumulation of measurement errors and inaccurate orientation/gravity corrections. Ex: 50m lost over 10 sec (cheapest) to 20 mins (fancy).
- **Truncation error**: Use of a finite sum to approximate an integral
- **Round-off error**: Use of floating-point numbers to represent real numbers

Numerical analysis quantifies all three.